

TO MAXIMIZE PD FOR A GIVEN
PFA = α DECIDE H_1 IF

$$L(\underline{x}) = \frac{p(\underline{x}; H_1)}{p(\underline{x}; H_0)} > \gamma$$

\uparrow LIKELIHOOD RATIO \uparrow RATIO OF "PROBABILITIES" THAT \underline{x} COMES FROM H_1 VS H_0

\uparrow THRESHOLD

TO FIND THRESHOLD USE PFA = α
CONSTRAINT.

NOTE THAT

$$R_1 = \{ \underline{x} : L(\underline{x}) > \gamma \}$$

EXAMPLE : PREVIOUS EXAMPLE

$$H_0 : x(0) = w(0)$$

$$H_1 : x(0) = 1 + w(0)$$

$$w(0) \sim N(0, 1) \quad . \quad \text{WANT PFA} = 10^{-3}$$

NEYMAN - PEARSON LEMMA SAYS
DECIDE H_1 IF

$$\frac{p(x|0); H_1}{p(x|0); H_0} > \gamma$$

$$\frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(x|0)-1)^2}}{\frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2|0}} > \gamma$$

$$e^{x|0)-1/2} > \gamma$$

LET $\gamma = e^\beta$ (WHY CAN'T γ
BE NEGATIVE?)

$$e^{x|0)-1/2} > e^\beta$$

$$\text{OR } x|0) > \beta + \frac{1}{2} = \underbrace{\ln \gamma + 1/2}_{\gamma'}$$

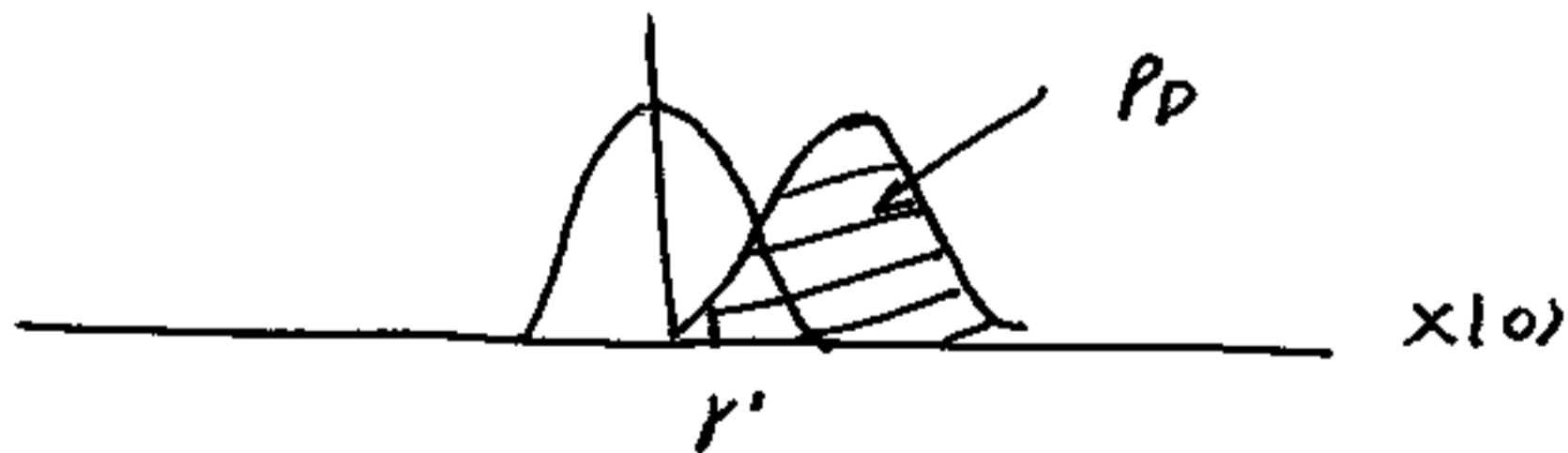
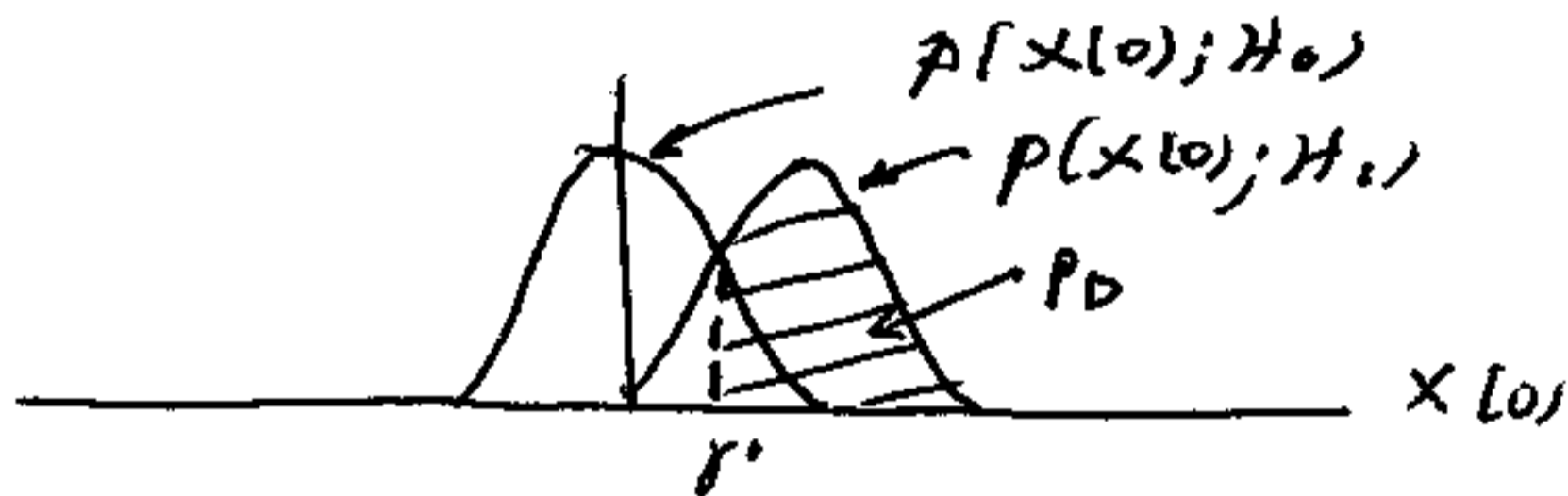
DECIDE H_1 IF $x|0) > \gamma'$. TO FIND
NEW THRESHOLD USE $PFA = 10^{-3}$

$$PFA = \int_{\gamma'}^{\infty} p(x|0); H_0) dx|0)$$

$\Rightarrow \gamma' = 3$. SAME DETECTOR AS BEFORE.

\Rightarrow OPTIMAL IN N-P SENSE
(LARGEST P_D FOR GIVEN PFA)

HOW CAN WE INCREASE P_D ?



PENALTY PAID?

EXAMPLE : DC LEVEL IN WGN

$$H_0 : x(n) = w(n) \quad n = 0, 1, \dots, N-1$$

$$H_1 : x(n) = A + w(n) \quad n = 0, 1, \dots, N-1$$

SIGNAL IS $s(n) = A > 0$

$w(n)$ IS WHITE GAUSSIAN NOISE

$$E(w(n)) = 0$$

$$E(w(m)w(n)) = \begin{cases} \sigma^2 & m = n \\ 0 & m \neq n \end{cases}$$

$$w(n) \sim N(0, \sigma^2)$$

DESIGN A N-P DETECTOR.

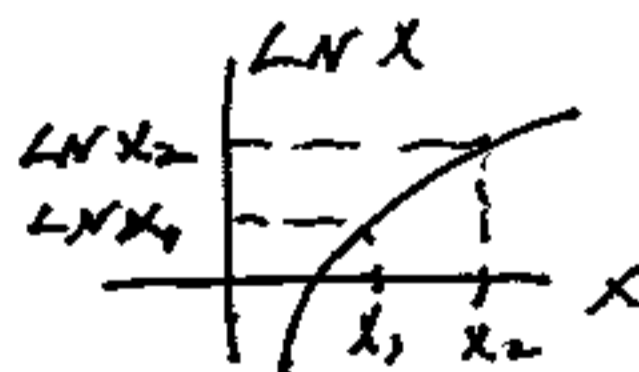
SOLUTION: TO MAXIMIZE P_D FOR
GIVEN $P_{FA} = \alpha$ DECIDE H_1
IF

$$\frac{p(x; H_1)}{p(x; H_0)} > \gamma$$

$$\frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} (x(n) - A)^2} > \gamma$$

$$\frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} x^2(n)}$$

TAKE LN BOTH SIDES



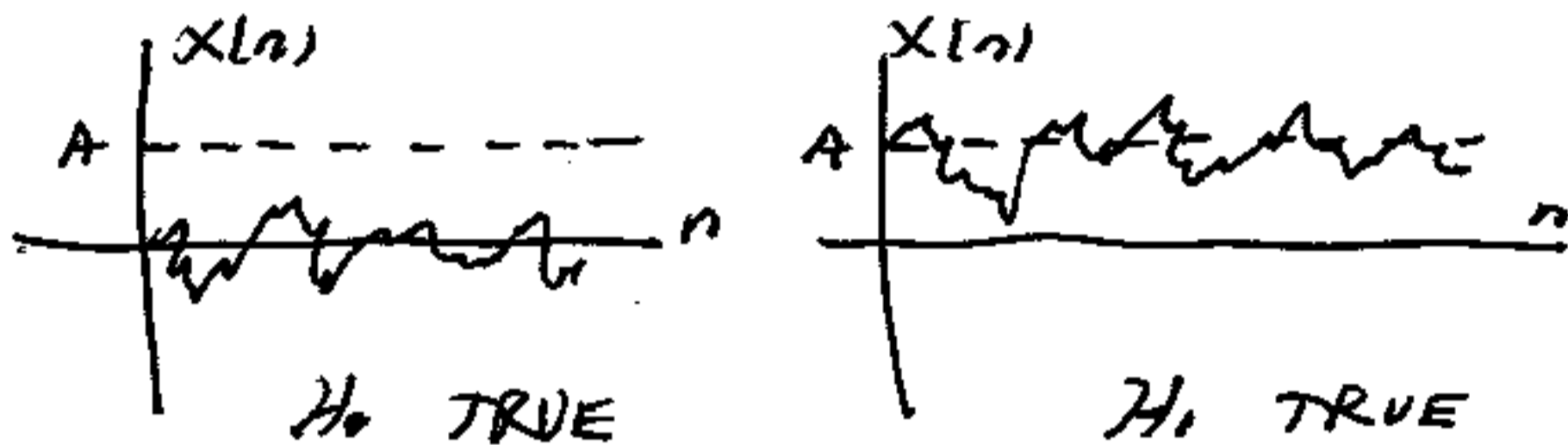
$$-\frac{1}{2\sigma^2} \left(-2A \sum_n x(n) + NA^2 \right) > \text{LN } \gamma$$

$$\frac{A}{\sigma^2} \sum_n x(n) > \text{LN } \gamma + \frac{NA^2}{2\sigma^2}$$

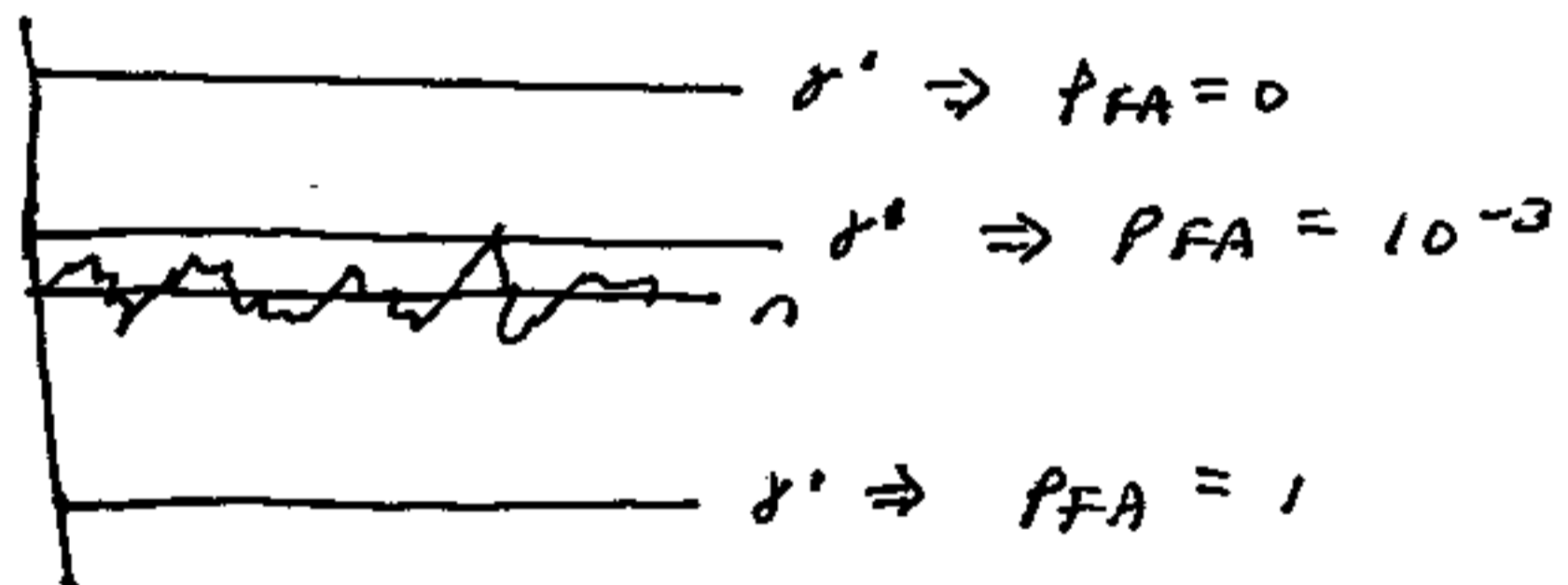
SINCE $A > 0$ (INEQUALITY DOESN'T
CHANGE DIRECTION)

$$\frac{1}{N} \sum_{n=0}^{N-1} x(n) > \frac{\sigma^2}{NA} \ln \delta + \frac{A}{2} = \delta'$$

COMPARE SAMPLE MEAN TO THRESHOLD



CHOICE OF δ' DEPENDS UPON PFA



PERFORMANCE EVALUATION

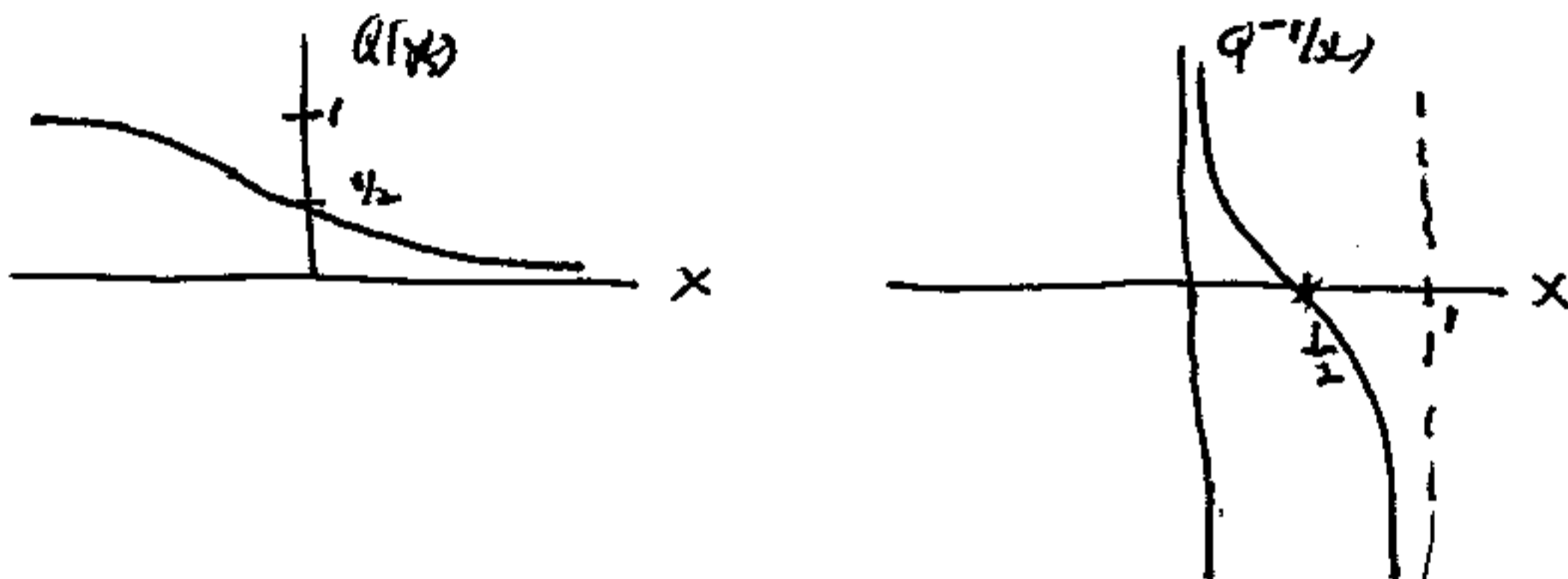
$$\text{LET } T(\underline{x}) = \frac{1}{N} \sum_{n=0}^{N-1} x(n)$$

UNDER H_0 $T(\underline{x}) \sim N(0, \sigma^2/N)$

$$PFA = P\{T(\underline{x}) > \delta'; H_0\}$$

$$= Q\left(\frac{\gamma^*}{\sqrt{\sigma^2/N}}\right)$$

OR $\gamma^* = \sqrt{\sigma^2/N} Q^{-1}(PFA)$



UNDER H_1 , $T(x) \sim N(A, \sigma^2/N)$

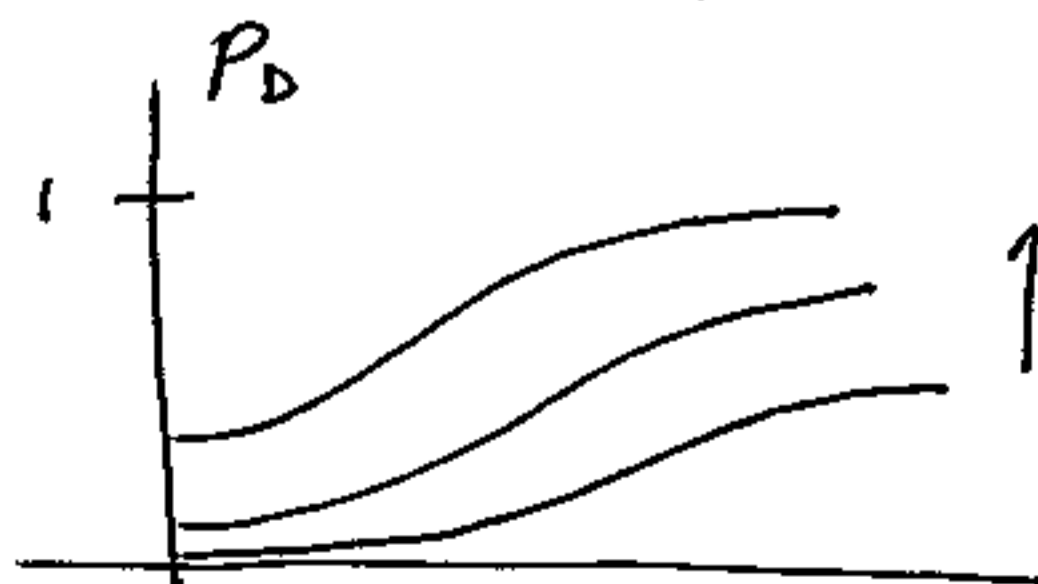
$$P_D = P_c \{ T(x) > \gamma^* ; H_1 \}$$

$$= Q\left(\frac{\gamma^* - A}{\sqrt{\sigma^2/N}}\right)$$

$$= Q\left(Q^{-1}(PFA) - \sqrt{\frac{A^2}{\sigma^2/N}}\right)$$

$$= Q\left(Q^{-1}(PFA) - \sqrt{\frac{NA^2}{\sigma^2}}\right)$$

ENERGY-TO-NOISE RATIO



$10 \log_{10} NA^2/\sigma^2$

FIG. 3.5

GIVEN. PFA, P_D DEPENDS ONLY ON

$$d^2 = \frac{NA^2}{\sigma^2}$$

$$= \frac{[E(T; H_1) - E(T; H_0)]^2}{\text{VAR}(T; H_0)}$$

CALLED DEFLECTION COEFFICIENT -
MEASURES DIFFERENCE BETWEEN
 $p(x; H_0)$ AND $p(x; H_1)$

P_D MONOTONICALLY INCREASES
WITH d^2 .

NOTE: $T(x)$ CALLED TEST STATISTIC
RECALL $\frac{1}{N} \sum |x_i|$ IS SUFFICIENT
STATISTIC. IF S.S. EXISTS,
THEN $T(x)$ WILL BE A FUNCTION
OF IT.

PARAMETER TESTS

PREVIOUS PROBLEM IS ACTUALLY A
PARAMETER TESTING PROBLEM.

UNDER \mathcal{H}_0 $\underline{x} \sim N(0, \sigma^2 \mathbf{I})$

UNDER \mathcal{H}_1 $\underline{x} \sim N(A \underline{1}, \sigma^2 \mathbf{I})$

$\underline{1} = [1 \dots 1]^T$. CONSIDER THE
FAMILY OF PDFS

$$p(\underline{x}; A) = \frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} (x(n) - A)^2}$$

DETECTION PROBLEM ASKS IF $A=0$
(NO SIGNAL) OR $A=A_1 > 0$ (SIGNAL
PRESENT) OR

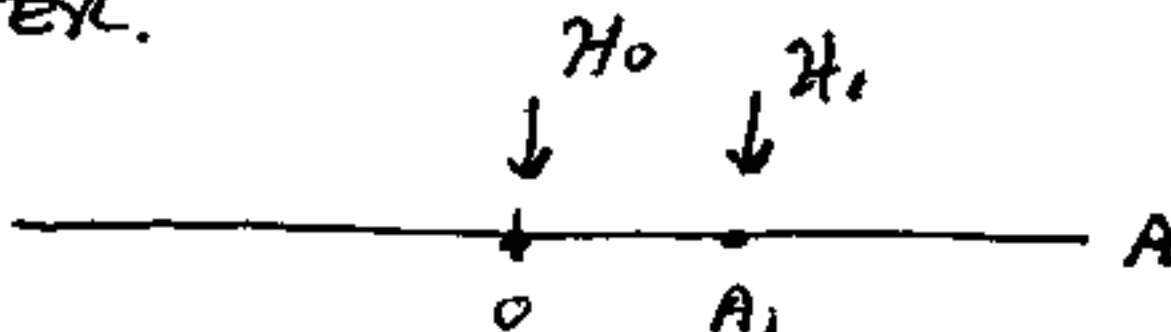
$$\mathcal{H}_0 : A = 0$$

$$\mathcal{H}_1 : A = A_1$$

N-P SOLUTION IS TO DECIDE \mathcal{H}_1 IF

$$\frac{p(\underline{x}; A=A_1)}{p(\underline{x}; A=0)} > \tau$$

THIS VIEWPOINT WILL BE USEFUL
LATER.



RECEIVER OPERATING CHARACTERISTICS (ROCS)

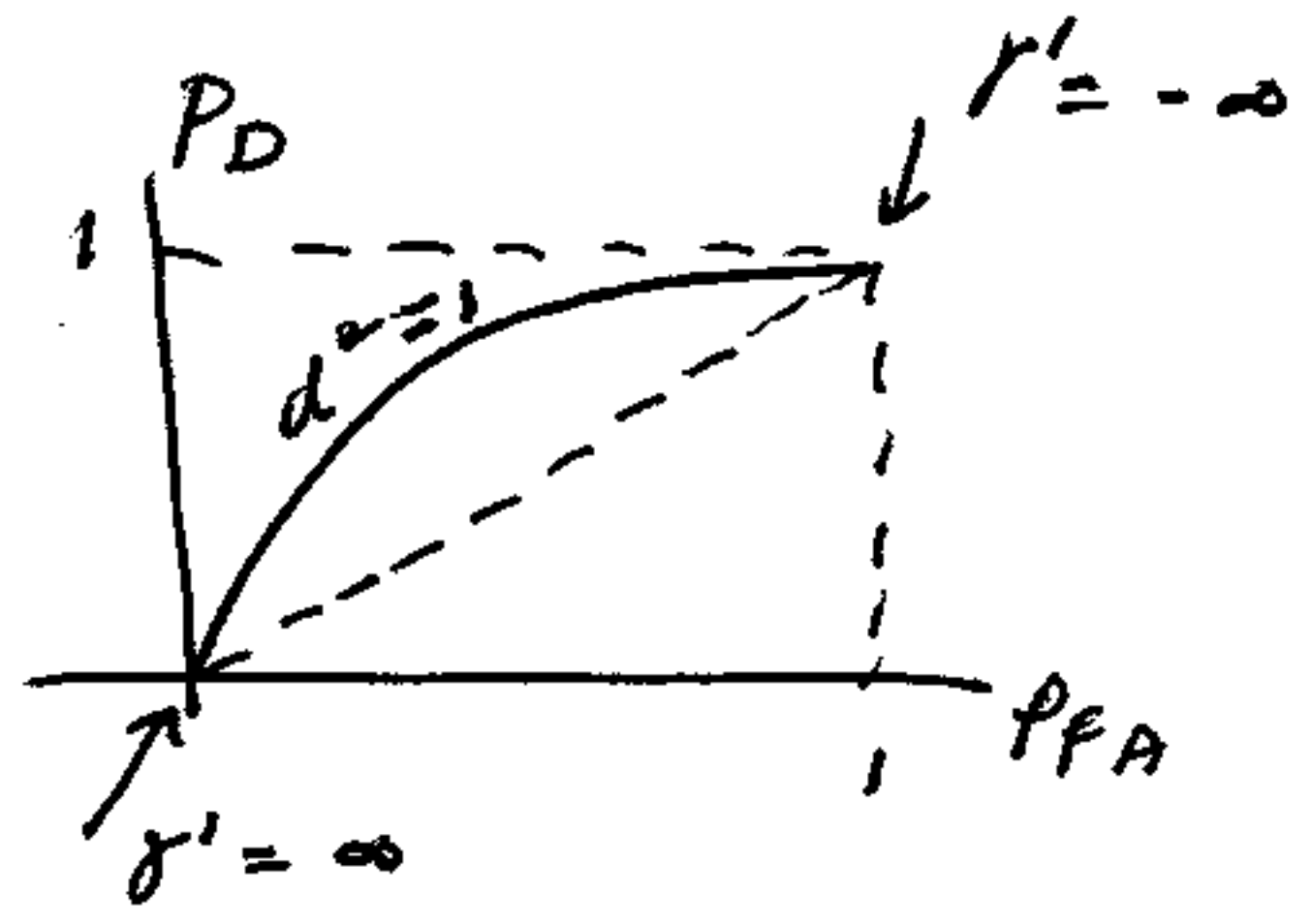
TO SUMMARIZE PERFORMANCE

$$P_D = Q(Q^{-1}(P_{FA}) - \sqrt{d^2})$$

WHERE $d^2 = NA^2/\sigma^2$

SEE
Q.M,
Q.I.V.M
CHAPTER 2

P_{FA}	P_D
10^{-3}	0.0183
10^{-2}	0.0924
10^{-1}	0.3891
1	1



AS WE RAISE THRESHOLD P_{FA} GOES DOWN BUT ALSO P_D .

ROC SHOULD BE ABOVE 45° LINE - ELSE WE CAN DO BETTER BY FLIPPING COIN

EXAMPLE : FLIP FAIR COIN

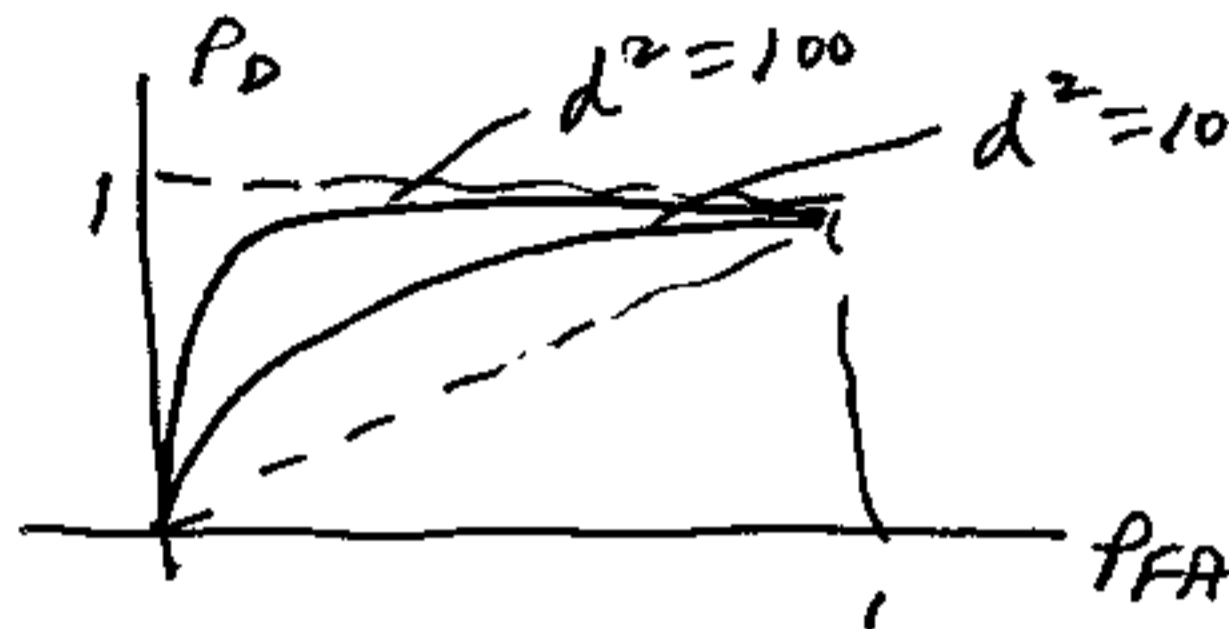
DECIDE H_1 IF HEADS

DECIDE H_0 IF TAILS

$$\Rightarrow P_{FA} = P_r \{ \text{TAILS} \} = 1/2$$

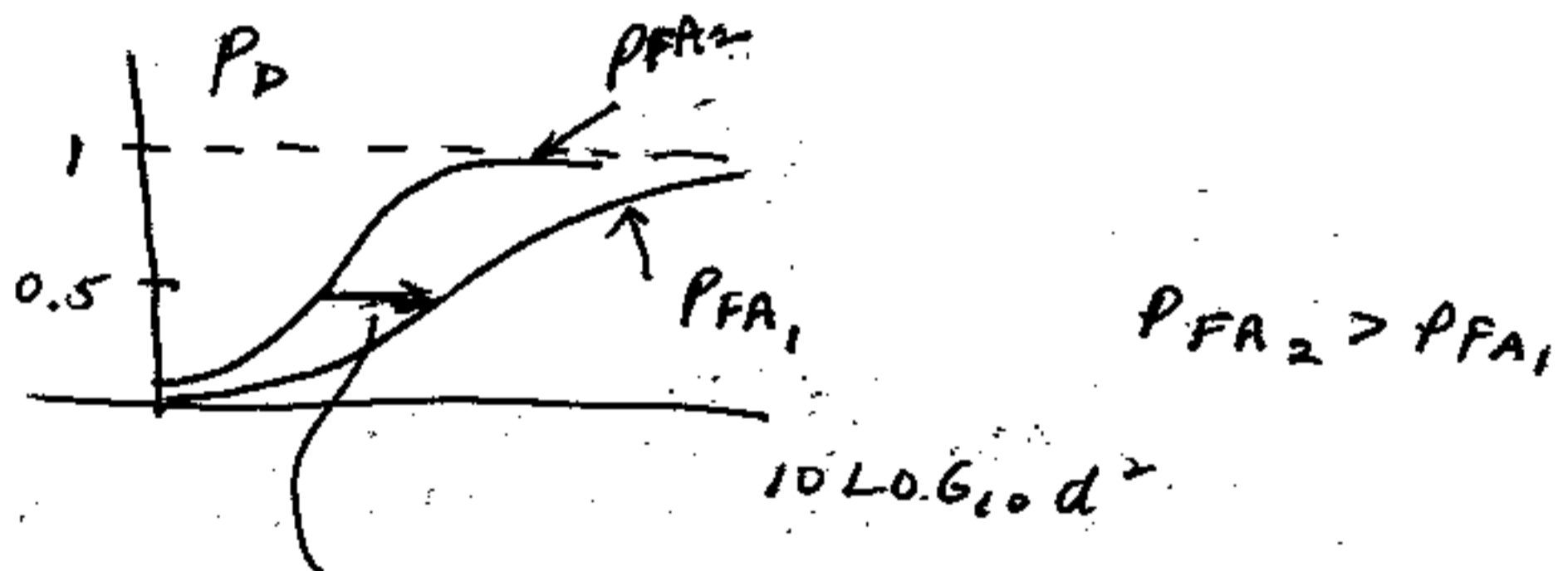
$$P_D = P_r \{ \text{HEADS} \} = 1/2$$

PERFORMANCE IMPROVES WITH d^2



FOR GIVEN PFA, P_D INCREASES.

ANOTHER WAY TO DISPLAY PERFORMANCE

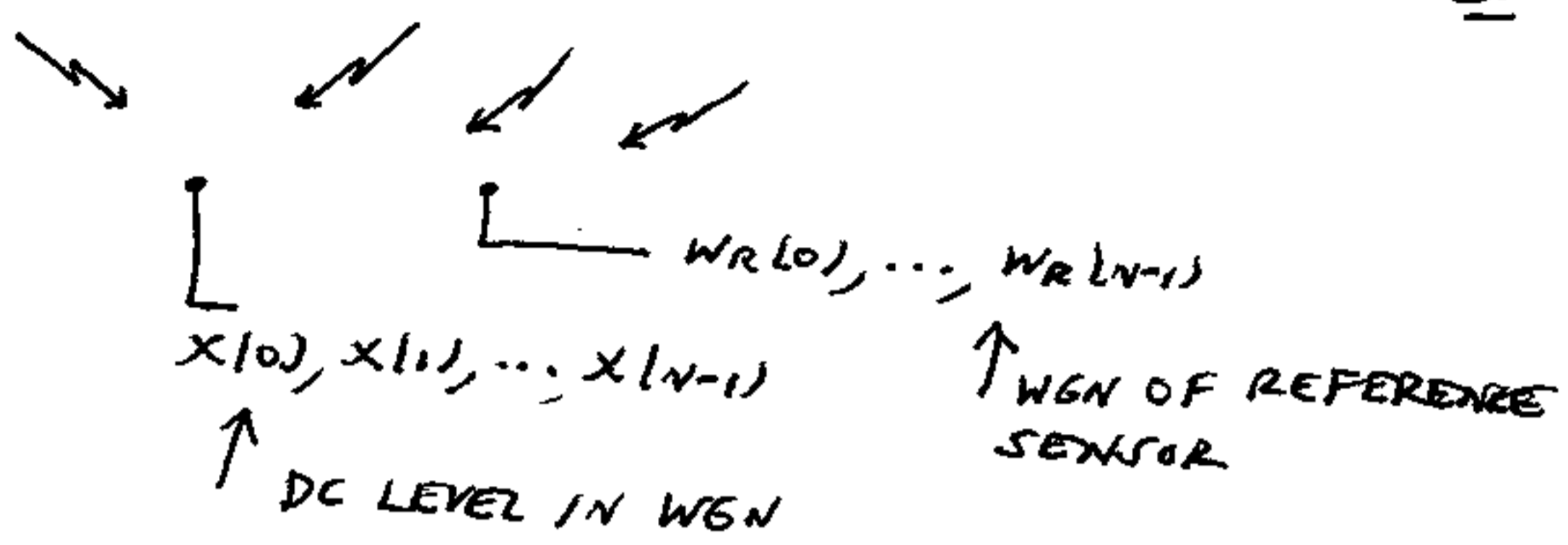


INCREASE IN SNR REQUIRED
FOR LOWER PFA.

IRRELEVANT DATA

WHEN CAN WE DISCARD DATA WITHOUT
REDUCING EFFECTIVENESS OF NP DETECTOR?

EXAMPLE : ARRAY PROCESSING



DEPENDS ON STATISTICAL RELATIONSHIP OF $w_R[n]$ TO $x[n]$. IF $w_R[n]$ IS INDEPENDENT OF $w[n]$, CAN DISCARD.

HOW ABOUT IF $w_R[n] = w[n]$?

CONSIDER $T'(z) = \frac{1}{N} \sum_{n=0}^{N-1} (x[n] - w_R[n])$

UNDER H_0 $T'(z) = 0$

UNDER H_1 $T'(z) = A$

⇒ IF $\gamma' = A/2$ PERFECT DETECTION FOR ANY PFA.

IN GENERAL CONSIDER TWO SETS OF DATA $\underline{x}_1, \underline{x}_2$. THE LIKELIHOOD RATIO IS

$$L(\underline{x}_1, \underline{x}_2) = \frac{p(\underline{x}_1, \underline{x}_2; H_1)}{p(\underline{x}_1, \underline{x}_2; H_0)}$$

$$= \frac{p(\underline{x}_2 | \underline{x}_1; H_1) p(\underline{x}_1; H_1)}{p(\underline{x}_2 | \underline{x}_1; H_0) p(\underline{x}_1; H_0)}$$

\rightarrow IF $= 1 \Rightarrow L(\underline{x}_1, \underline{x}_2)$ DOESN'T
 DEPEND ON $\underline{x}_2 \Rightarrow$
 \underline{x}_2 IS IRRELEVANT

$$p(\underline{x}_2 | \underline{x}_1; H_0) = p(\underline{x}_2 | \underline{x}_1; H_1)$$

GIVEN \underline{x}_1 , PDF OF \underline{x}_2 DOESN'T
 DEPEND ON WHICH HYPOTHESIS
 IS TRUE.

EXAMPLE 1 SPECIAL CASE - DC LEVEL
 IN WGN - EXTRA NOISE SAMPLES

$$p(\underline{x}_2 | \underline{x}_1; H_0) = p(\underline{x}_2; H_0) = p(\underline{x}_2; H_1) = p(\underline{x}_2 | \underline{x}_1; H_1)$$

$$H_0: x(n) = w(n) \quad n = 0, 1, \dots, 2N-1$$

$$H_1: x(n) = A + w(n) \quad n=0, 1, \dots, N-1$$

$$w(n) \quad n=N, \dots, 2N-1$$

$w(n)$ IS $WGN \Rightarrow \{w(0), \dots, w(N-1)\}$
IS INDEPENDENT OF $\{w(N), \dots, w(2N-1)\}$

$$\Rightarrow \underline{x}_2 = [w(N) \dots w(2N-1)]^T$$

$$p(\underline{x}_2; H_0) = \frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} x_2^2(n)}$$

$$= p(\underline{x}_2; H_1)$$

WHAT IF $w(n)$ IS COLORED NOISE?

CONCLUSION : FOR DETECTION IN WGN
LIMIT OBSERVATION INTERVAL
TO SIGNAL INTERVAL.

MINIMUM PROB. OF ERROR

MAKES SENSE AT TIMES TO CONSIDER
 H_0, H_1 AS RANDOM EVENTS AND ASSIGN
PRIOR PROBABILITIES

EXAMPLE : RADAR DETECTION

$$P(H_0) = P\{\text{NO TARGET}\} = ?$$

DIGITAL COMMUNICATIONS - EQUALLY
LIKELY FOR "0" OR "1" TO BE SENT

$$H_0: \text{"0" SENT} \quad P(H_0) = \frac{1}{2}$$

$$H_1: \text{"1" SENT} \quad P(H_1) = \frac{1}{2}$$

ALLOWS US TO DEFINE PROBABILITY
OF ERROR P_e

BAYESIAN APPROACH - MUST BE
CAREFUL

IF WE ASSIGN $P(H_1) = 0.99$,
WHAT WILL DETECTOR DO?

DEFINE P_e AS

$$P_e = P\{\text{DECIDE } H_0, H_1 \text{ TRUE}\} \\ + P\{\text{DECIDE } H_1, H_0 \text{ TRUE}\}$$

$$= \underbrace{P\{\text{DECIDE } H_0 | H_1 \text{ TRUE}\}}_{P(H_0|H_1)} \underbrace{P\{H_1 \text{ TRUE}\}}_{P(H_1)} \\ + \underbrace{P\{\text{DECIDE } H_1 | H_0 \text{ TRUE}\}}_{P(H_1|H_0)} \underbrace{P\{H_0 \text{ TRUE}\}}_{P(H_0)}$$

CAN BE SHOWN THAT TO MINIMIZE P_e SHOULD DECIDE H_1 IF

$$\frac{p(x|H_1)}{p(x|H_0)} > \frac{p(H_0)}{p(H_1)} = \gamma$$

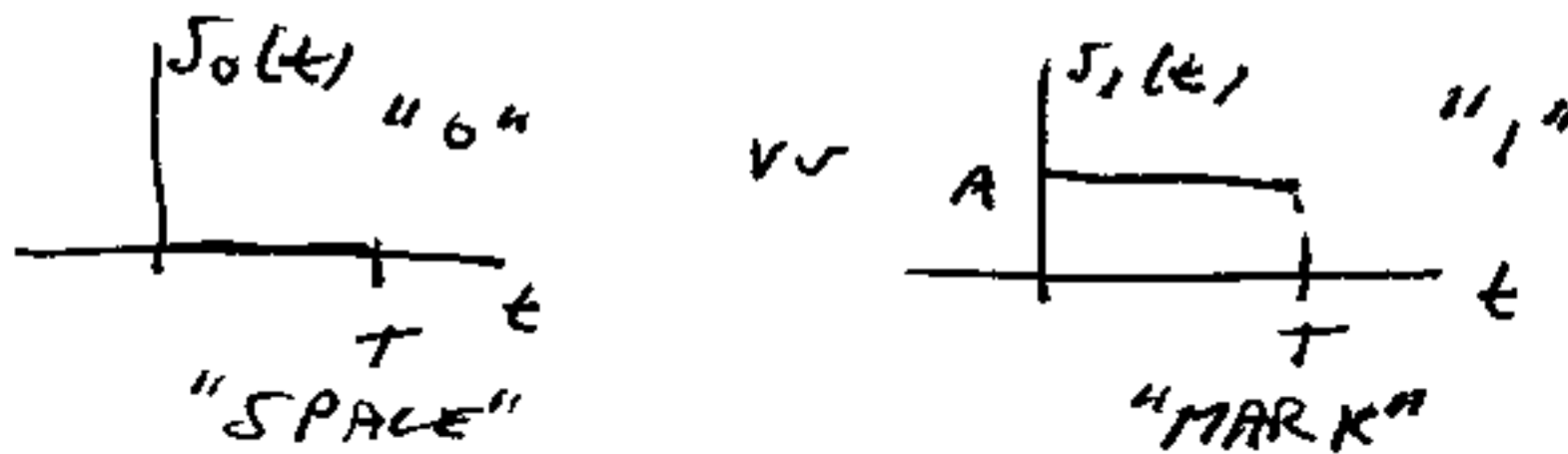
↑ CONDITIONAL LIKELIHOOD RATIO

EXAMPLE : $p(H_0) = p(H_1) \Rightarrow$

CHOOSE H_1 IF $p(x|H_1) > p(x|H_0)$
OR MORE LIKELY HYPOTHESIS

CALLLED A MAXIMUM LIKELIHOOD (ML) DETECTOR

EXAMPLE : DC LEVEL IN WGN OR ON-OFF COMM. SYSTEM



AFTER SAMPLING RECEIVED WAVEFORM :

$$H_0: x(n) = w(n) \quad n = 0, 1, \dots, N-1$$

$$H_1: x(n) = A + w(n) \quad n = 0, 1, \dots, N-1$$

$A > 0$, $w(n)$ is WGN, $P(H_0) = P(H_1)$.

THUS, $r = 1$ AND WE DECIDE H_1 IF

$$\frac{P(\underline{x} | H_1)}{P(\underline{x} | H_0)} > 1$$

$$\frac{\frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{1}{2\sigma^2} \sum_n (x(n)-A)^2}}{\frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{1}{2\sigma^2} \sum_n x^2(n)}} > 1$$

TAKE LN \Rightarrow

$$-\frac{1}{2\sigma^2} \left(-2A \sum_n x(n) + NA^2 \right) > 0$$

$$\Rightarrow \bar{x} > A/2 \quad \bar{x} = \frac{1}{N} \sum_{n=0}^{N-1} x(n)$$

(SAMPLE MEAN)

SAME AS FOR N-P EXCEPT FOR THRESHOLD (CHOSEN TO MINIMIZE P_e)

WHAT IS P_e ?

$$\begin{aligned}\bar{X} &\sim N(0, \sigma^2/N) && \text{COND. ON } H_0 \\ &\sim N(A, \sigma^2/N) && \text{COND. ON } H_1\end{aligned}$$

$$\begin{aligned}P_e &= \frac{1}{2} [P(H_0|H_1) + P(H_1|H_0)] \\ &= \frac{1}{2} [P_r\{\bar{X} < \frac{A}{2} | H_1\} + P_r\{\bar{X} > \frac{A}{2} | H_0\}] \\ &= \frac{1}{2} \left[1 - Q\left(\frac{A/2 - A}{\sqrt{\sigma^2/N}}\right) + Q\left(\frac{A/2}{\sqrt{\sigma^2/N}}\right) \right] \\ &= Q\left(\sqrt{\frac{NA^2}{4\sigma^2}}\right)\end{aligned}$$

↑ NOTE NA^2/σ^2

NEED $NA^2/\sigma^2 = 108$ OR ≈ 20 dB FOR $P_e = 10^{-7}$

ALTERNATIVE FORM OF MIN PE DETECTOR:

DECIDE H_1 IF

$$p(x|H_1)P(H_1) > p(x|H_0)P(H_0)$$

$$\text{BUT } P(H_i|x) = \frac{p(x|H_i)P(H_i)}{p(x)}$$

$p(x)$ (BAYES' RULE)

WHERE $p(x) = p(x|H_0)P(H_0) + p(x|H_1)P(H_1)$

DOESN'T DEPEND ON $H_i \Rightarrow$

DECIDE H_1 IF

$$P(H_1 | x) > P(H_0 | x)$$

GIVEN DATA CHOOSE HYPOTHESIS WITH GREATER PROBABILITY.

MAXIMUM A POSTERIORI (MAP) DETECTOR \uparrow AFTER DATA OBSERVED

WHAT IS EFFECT OF $P(H_0)$, $P(H_1)$ ON DECISION REGIONS? SEE FIG. 3.10.

READ ABOUT BAYES RISK

MULTIPLE HYPOTHESES

N-P DOESN'T EASILY EXTEND - HAVE TO ASSIGN TOO MANY ERROR PROBABILITIES

	H_0	H_1	H_2	
H_0		?	?	$P(H_0; H_j)$
H_1	?		?	
H_2	?	?		

MIN. P_e DOES

MULTIPLE HYPOTHESIS TESTING \equiv

DISCRIMINATION \equiv CLASSIFICATION

$$\begin{aligned}
 P_e &= \sum_{i=0}^{M-1} \sum_{\substack{j=0 \\ i \neq j}}^{M-1} P(H_i, H_j) \\
 &= \sum_{i=0}^{M-1} \sum_{\substack{j=0 \\ i \neq j}}^{M-1} P(H_i | H_j) P(H_j)
 \end{aligned}$$

TO MINIMIZE P_e DECIDE H_k IF

$$P(H_k | x) > P(H_i | x) \quad i \neq k$$

MAP RULE.

PROOF :

$$P(H_i | H_j) = \int_{R_i} p(x | H_j) dx$$

$$P_e = \sum_{i=0}^{M-1} \sum_{\substack{j=0 \\ i \neq j}}^{M-1} \int_{R_i} p(x | H_j) P(H_j) dx$$

$$= \sum_i \int_{R_i} \underbrace{\sum_{\substack{j \\ j \neq i}} p(x | H_j) P(H_j)}_{\geq 0} dx$$

TO MINIMIZE P_e NOTE THAT WE HAVE TO ASSIGN EACH x TO ONE AND ONLY ONE DECISION REGION.

CONSIDER $x = x_0$ AND ASSIGN IT TO R_2 . THEN, P_e INCREASES BY

$$\sum_{\substack{j \\ j \neq 2}} p(x_0 | H_j) P(H_j) dx$$

IF WE ASSIGN IT TO R_3 WE INCUR

$$\sum_{\substack{j \\ j \neq 3}} p(x_0 | H_j) P(H_j) dx$$

THUS, ASSIGN x TO R_k IF

$$\sum_{\substack{j \\ j \neq k}} p(x | H_j) P(H_j) \text{ IS MINIMUM}$$