

9) Using (3.32)

$$\mathbf{I}(A) = \left(\frac{\partial \underline{\mu}(A)}{\partial A} \right)^T \underline{\Sigma}^{-1} \frac{\partial \underline{\mu}(A)}{\partial A}$$

$$\underline{\mu}(A) = [A \ A]^T \Rightarrow \frac{\partial \underline{\mu}(A)}{\partial A} = \underline{1}$$

$$\text{var}(\hat{A}) \geq \frac{1}{\mathbf{1}^T \underline{\Sigma}^{-1} \mathbf{1}} \quad (\text{or use approach of Prob 3.5})$$

$$\underline{\Sigma}^{-1} = \frac{\frac{1}{\sigma^2} \begin{bmatrix} 1 & -\rho \\ -\rho & 1 \end{bmatrix}}{1 - \rho^2}$$

$$\Rightarrow \text{var}(\hat{A}) \geq \frac{\sigma^2(1 - \rho^2)}{2 - 2\rho} = \frac{\sigma^2}{2} (1 + \rho)$$

If $\rho = 0$, $\text{var}(\hat{A}) \geq \sigma^2/2$, as expected.
 If $\rho \rightarrow 1$, $\text{var}(\hat{A}) \geq \sigma^2$. This is the same bound as for one sample and occurs because as $\rho \rightarrow 1$, $W[0]$ and $W[1]$ will be equal. Hence, we have only one independent data sample. If $\rho \rightarrow -1$, $\text{var}(\hat{A}) \geq 0$ and in fact, in this case $W[0] = -W[1]$.
 Thus,

$$\begin{aligned}
 \hat{A} &= \frac{1}{2}(X[0] + X[1]) \\
 &= \frac{1}{2}(A + W[0] + A - W[0]) = A
 \end{aligned}$$

for any realization of the noise samples. Additivity property of Fisher information only holds for independent samples. In this example we could have

$$i(A) \leq I(A) < \infty i(A)$$

where $i(A) = 1/\sigma^2$.